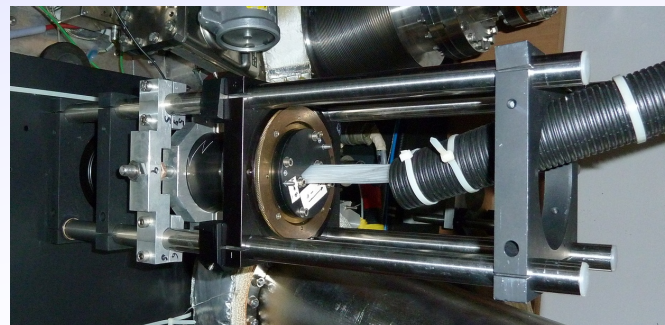
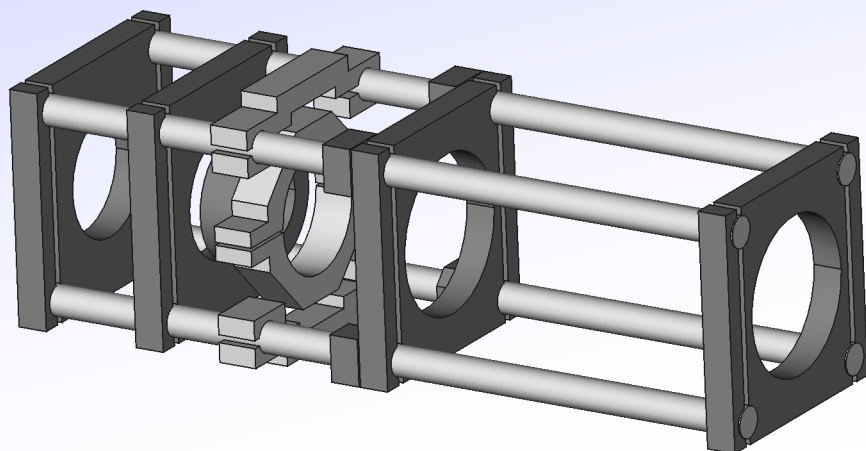
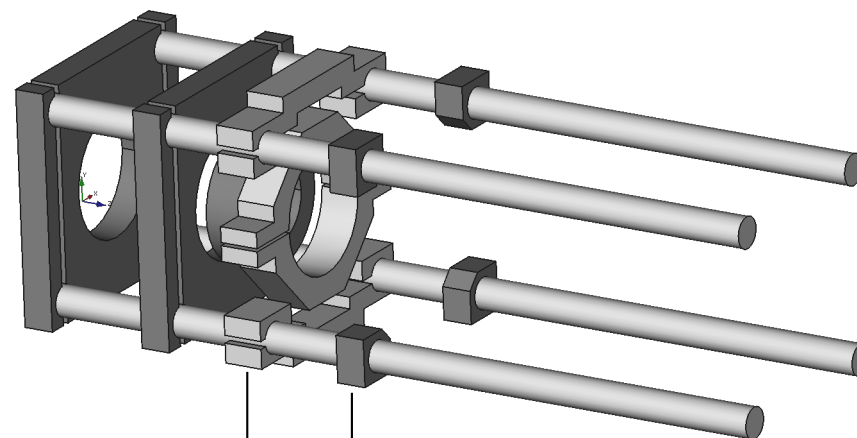


IMSE Design - Mechanical - Overview

The existing MSE system at ASDEX Upgrade looks like this:

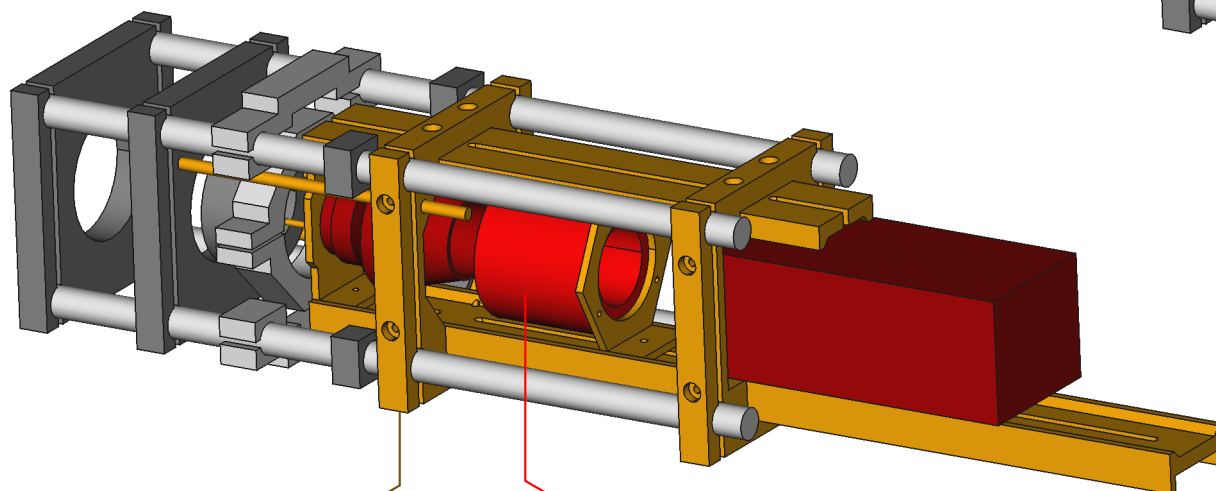


1) Remove fibres, fibre holder block and mount plates, leaving the 4 main rails, positioning stubs and the silver clamp:



Fibre positioning stubs.
Fibre holder clamp.

2) Build the IMSE system (at HGW) as a complete unit which slides on to the 4 rails. It must avoid the positioning stubs and the fibre holder clamp:



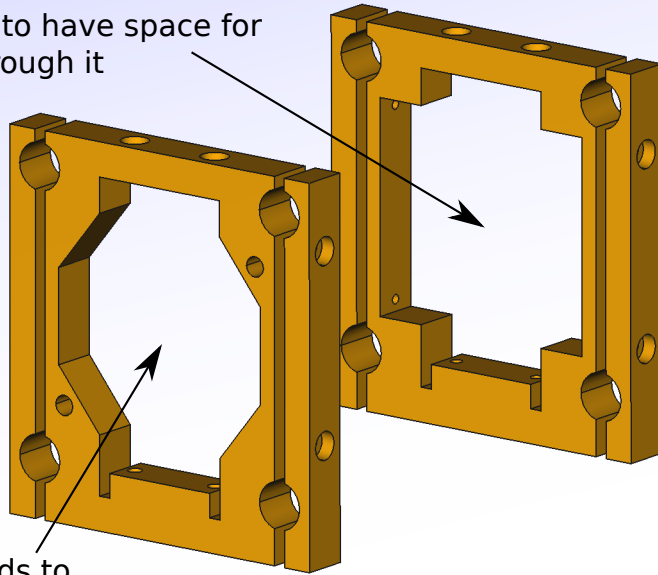
IMSE Carriage

Optical Components

IMSE Design - Mechanical - Carriage

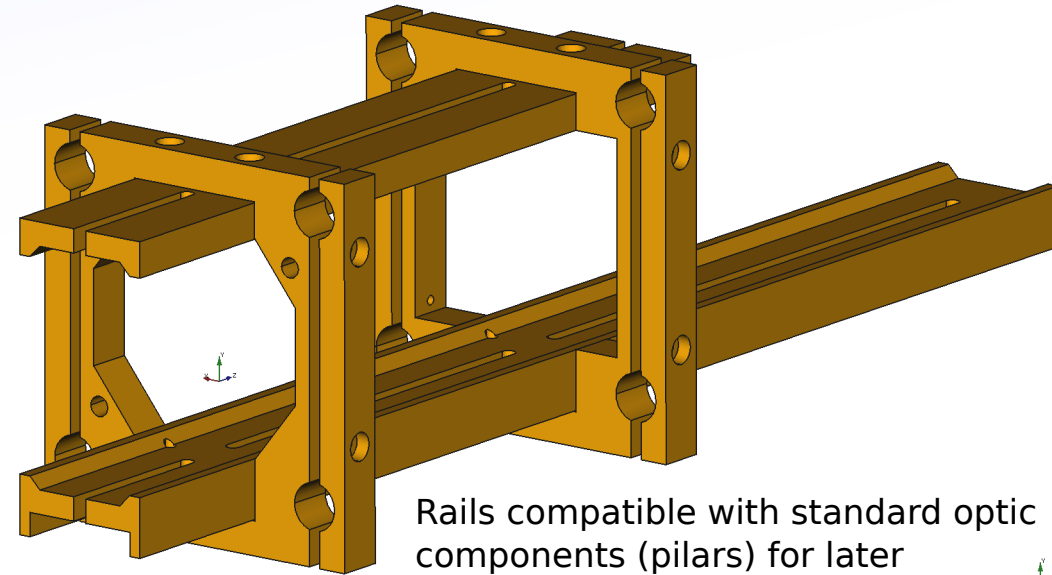
1) Build mounting plates based on the existing end plate design:

Rear mount needs to have space for camera to pass through it (93x78 mm)



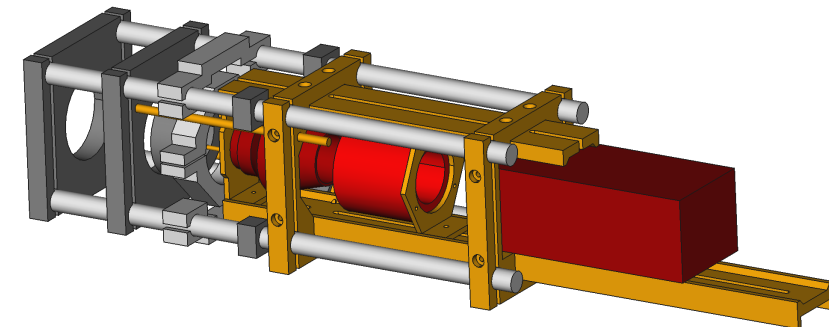
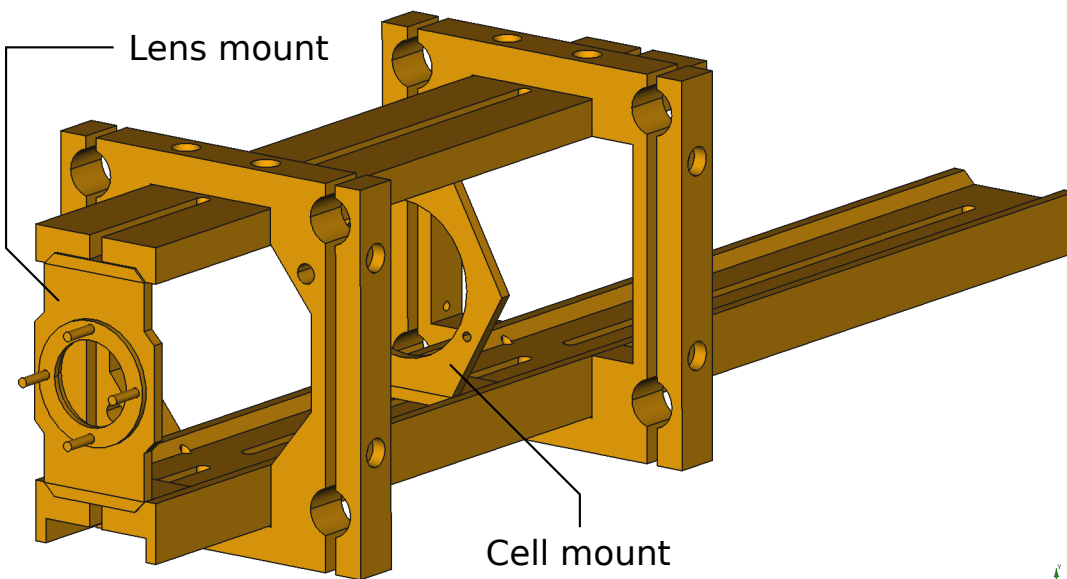
Forward mount needs to have space for cell + lenses to pass through it ($\varnothing 100\text{mm}$)

2) Add top and bottom rails that keep carriage stiff and allow optical element mounts to slide along:



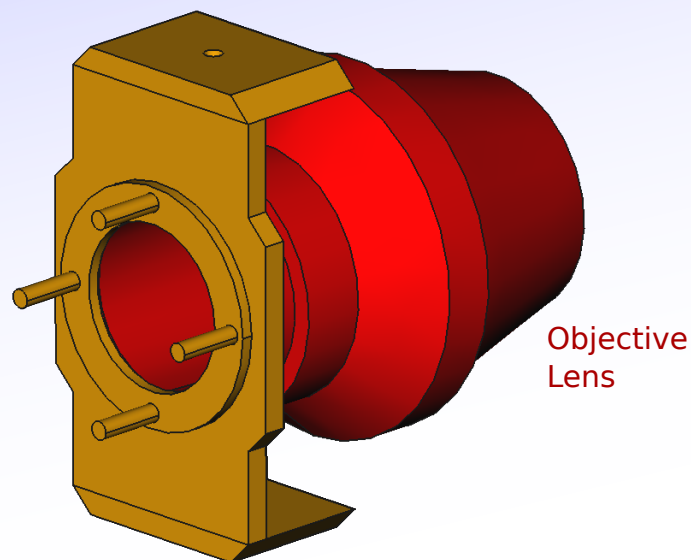
Rails compatible with standard optic components (pillars) for later extension (field lenses etc)

3) Build mounts for lens and the optical cell/oven:

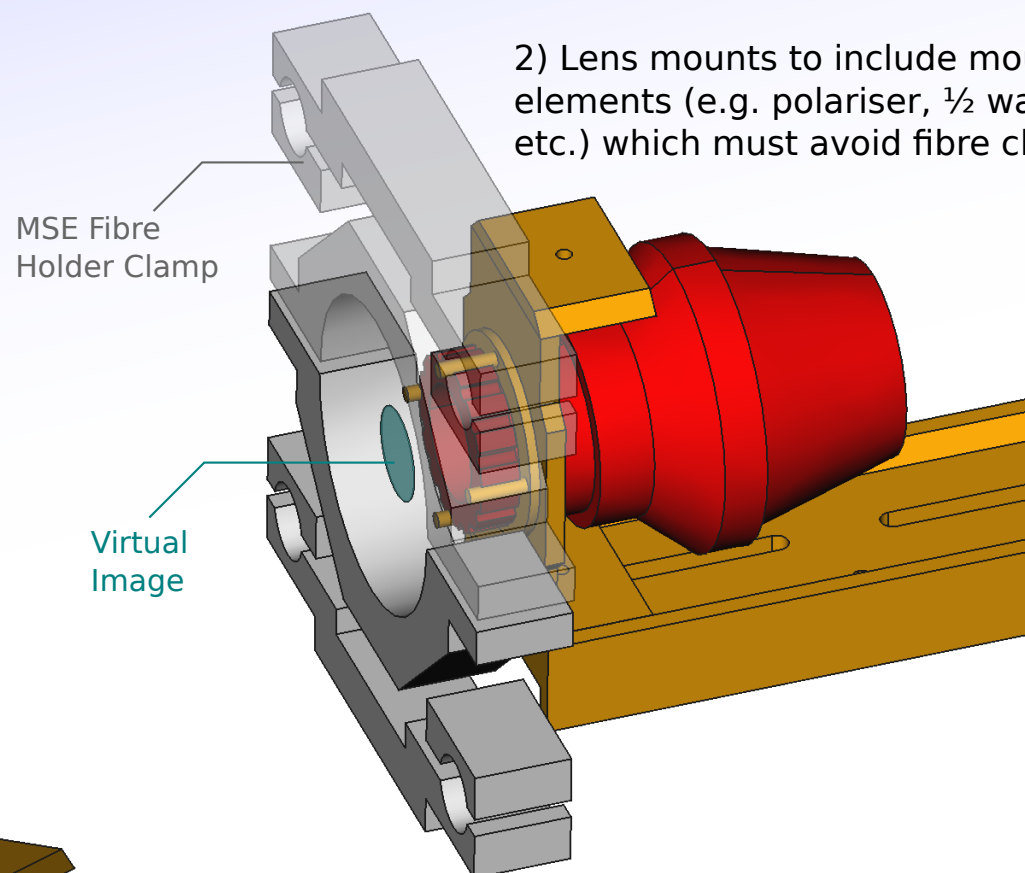


IMSE Design - Mechanical - Lens Mounts

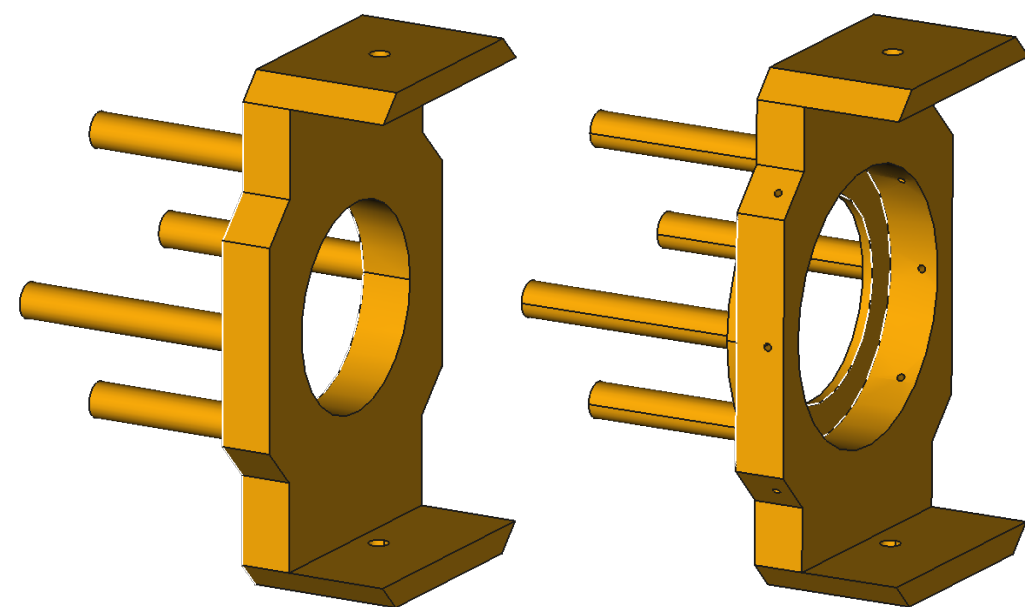
- 1) Objective lens mount, self-locates into rails fixed to system optical axis:



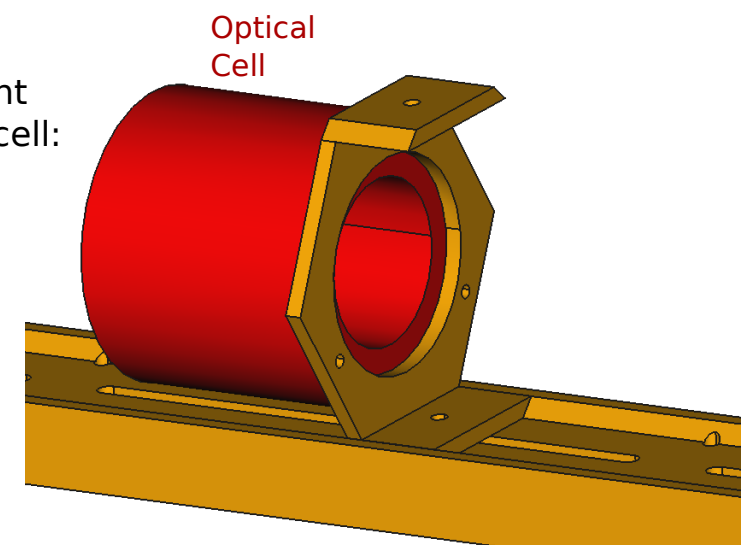
- 2) Lens mounts to include mount for cell elements (e.g. polariser, $\frac{1}{2}$ wave plate etc.) which must avoid fibre clamp:



- 3) One for M42 thread lenses and one for Canon EF bayonet (and adapter to Nikon):

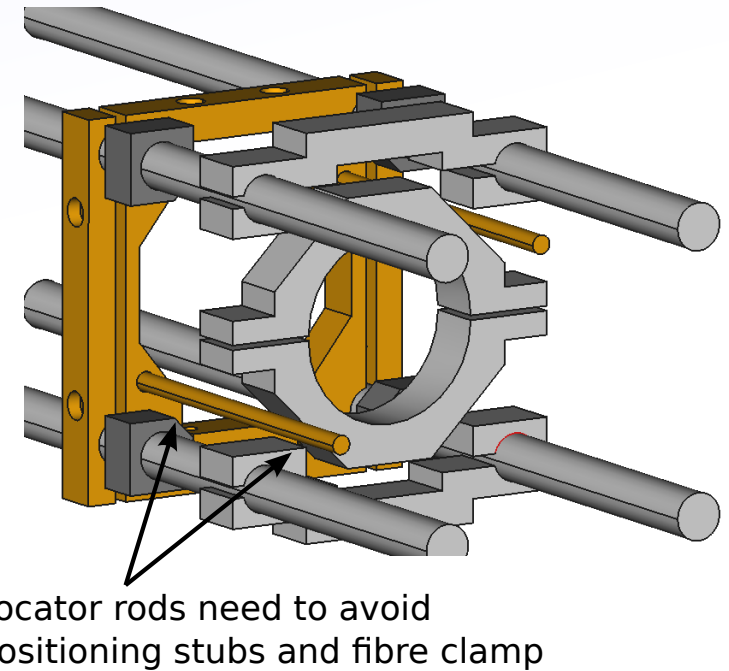
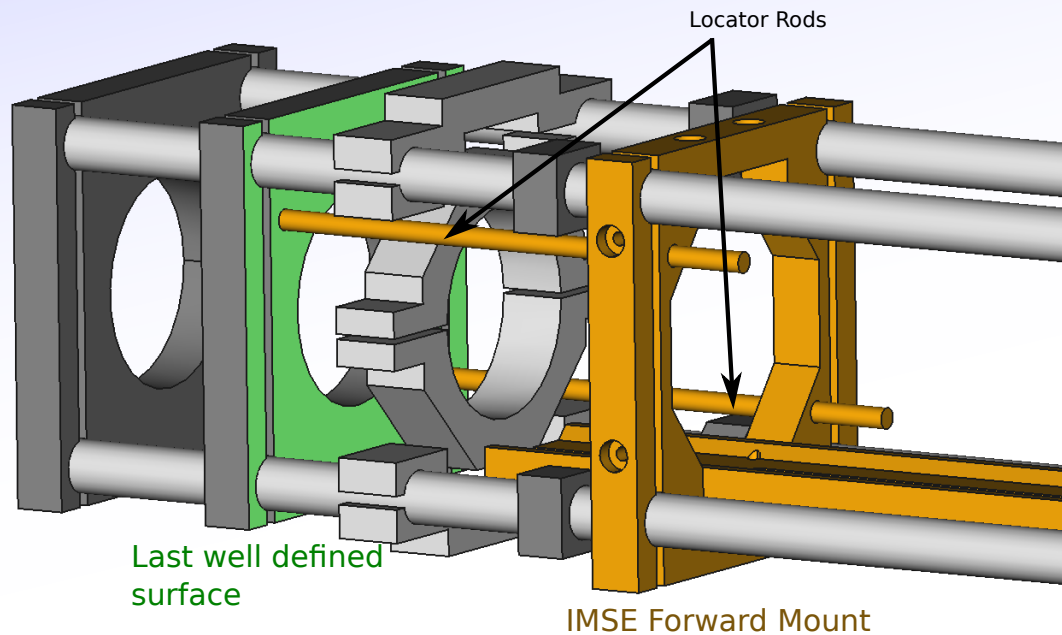


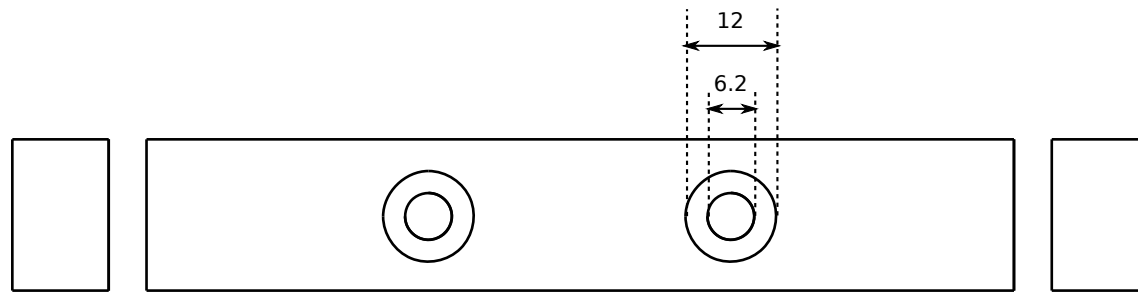
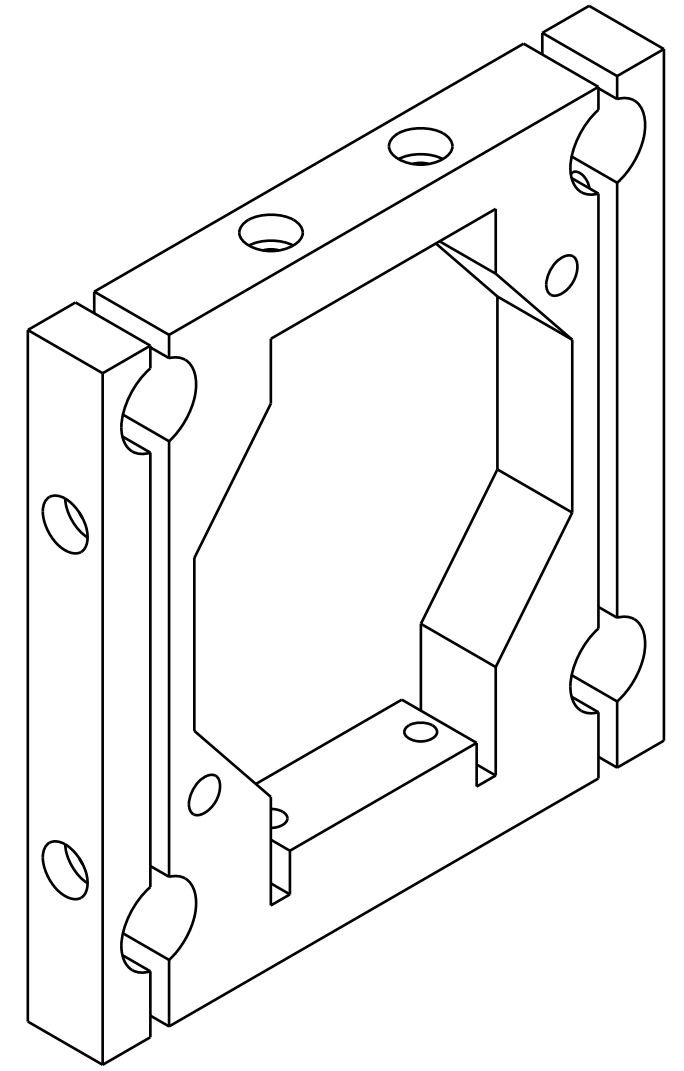
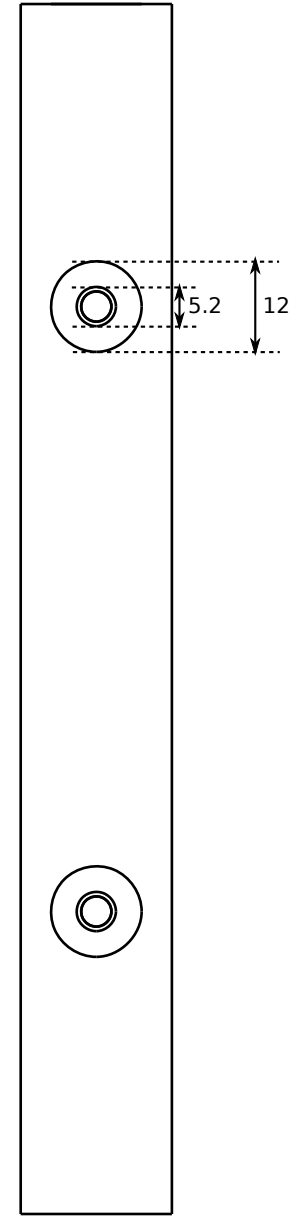
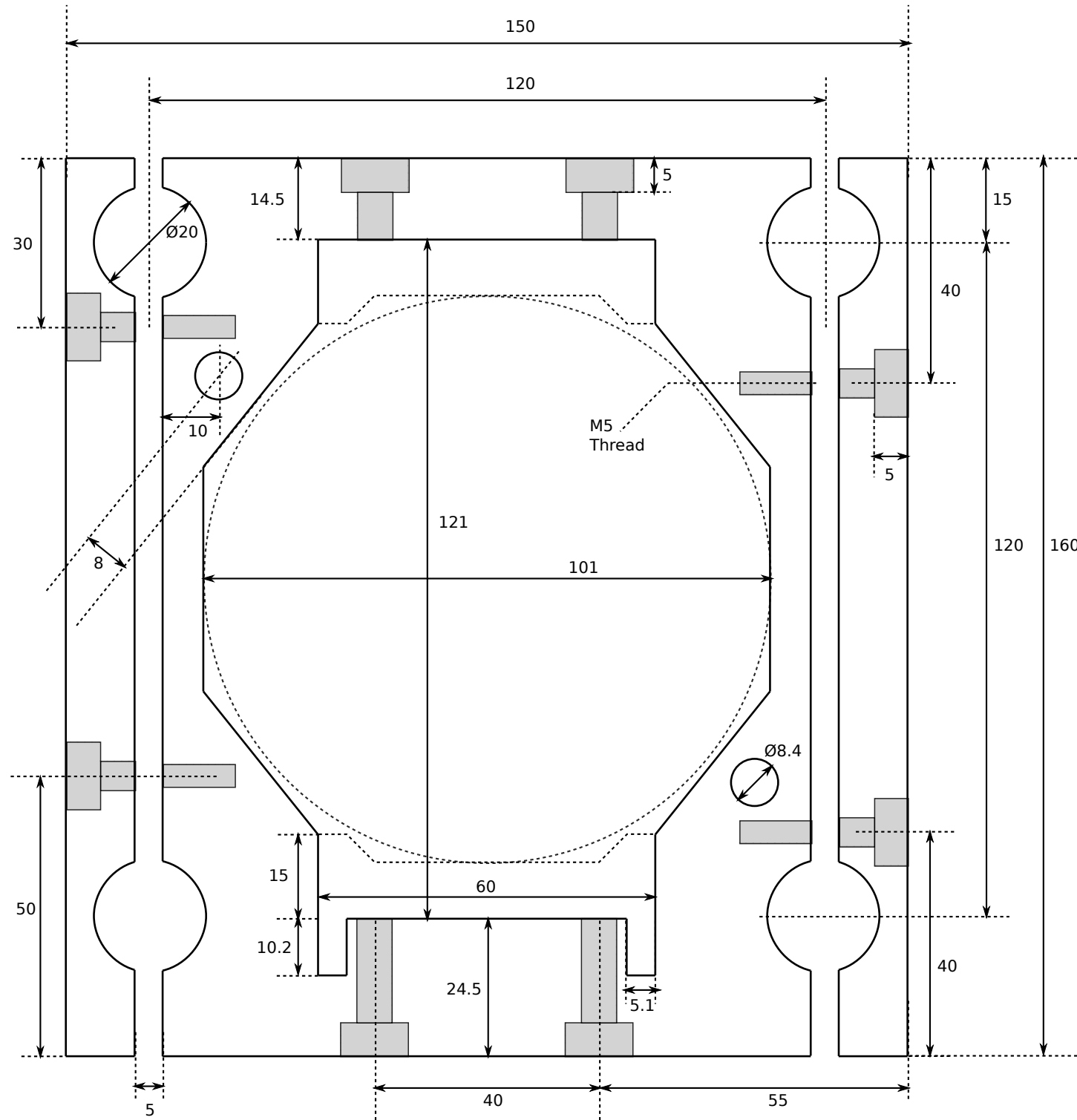
- 4) Similar mount for the optical cell:



IMSE Design - Mechanical - Locator Rods

We can't be completely sure where the clamp or the positioning stubs are, so need to locate the IMSE system from the last precisely known plane:

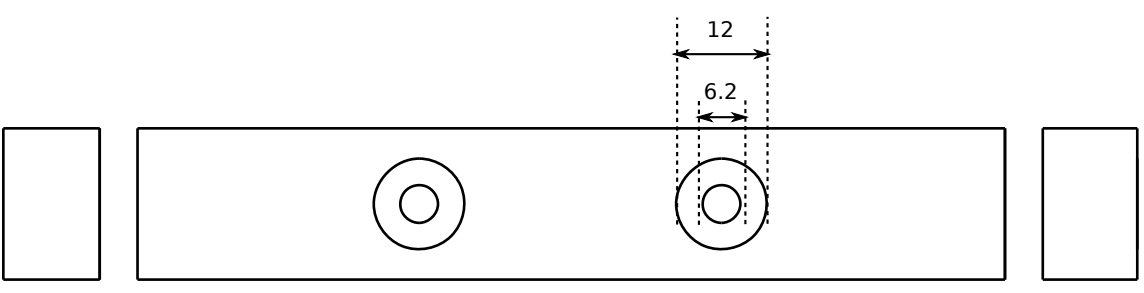
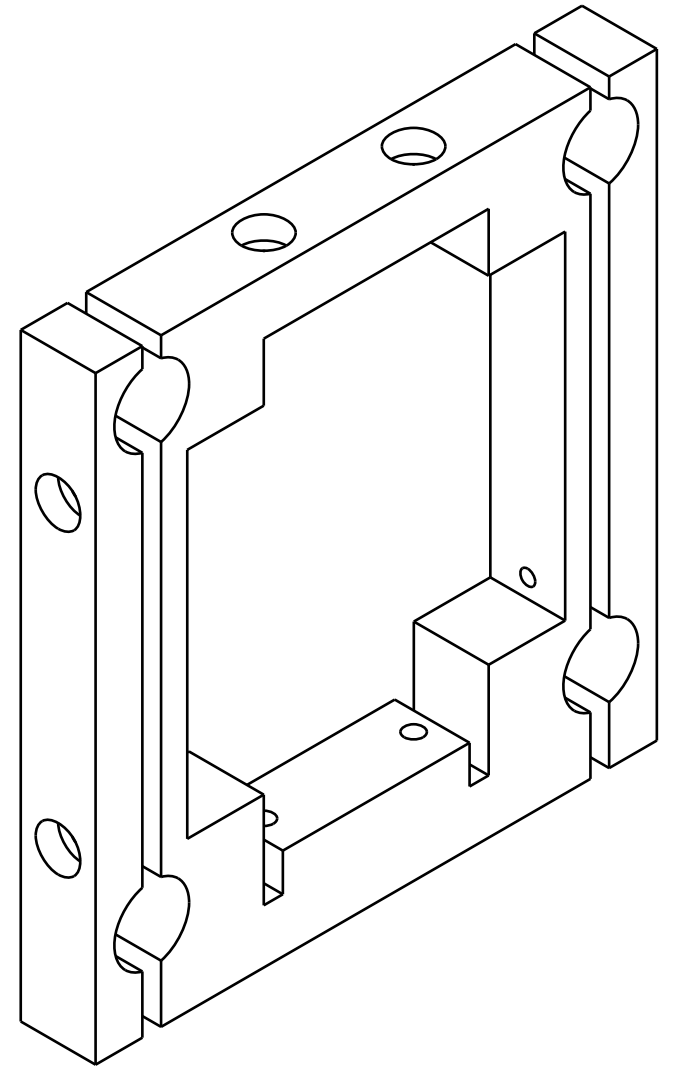
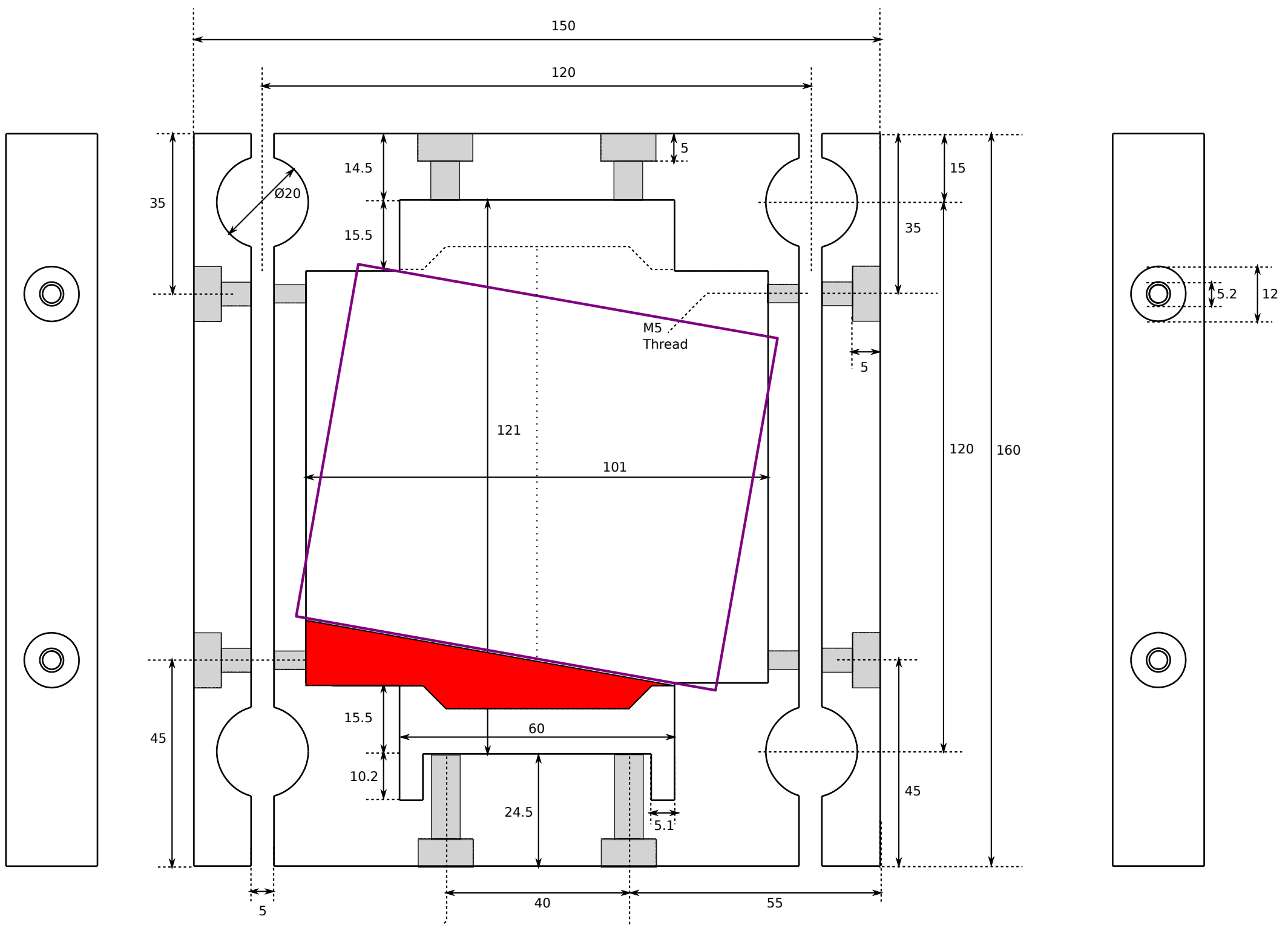



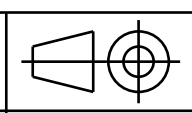


DESIGNED BY: OLIVER FORD	<h1>IMSE Carriage</h1> <p>Forward Rail Mount</p>		I	-
DATE: 20/06/2012			H	-
CHECKED BY:			G	-
DATE:			F	-
SIZE A3			E	-
SCALE 1:1	WEIGHT (kg)		D	-
DRAWING NUMBER 1			C	-
		SHEET 1	B	-
This drawing is our property; it can't be reproduced or communicated without our written agreement.			A	-

H G F E D C B A

4 3 2 1



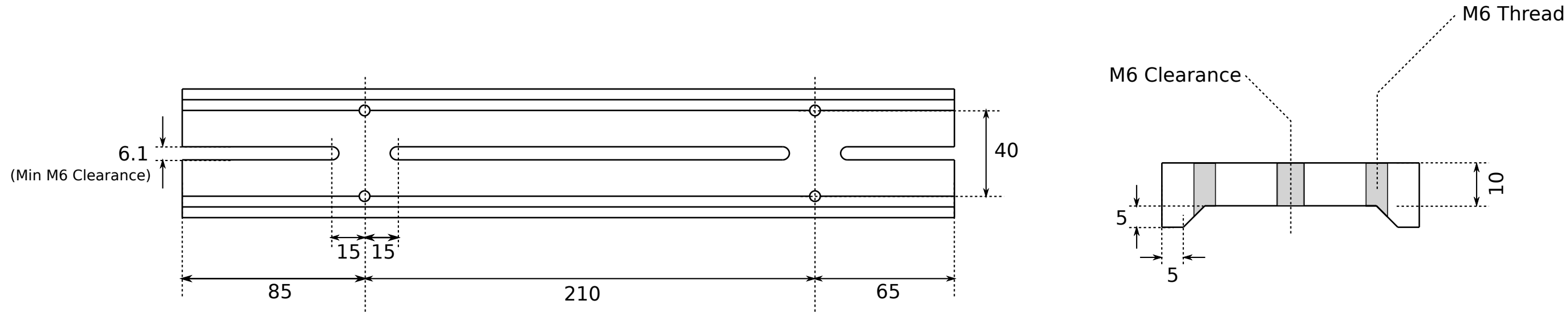
DESIGNED BY: OLIVER FORD		<h1>IMSE Carriage</h1> Rear Rail Mount		I	-
DATE: 20/06/2012				H	-
CHECKED BY:				G	-
DATE:				F	-
SIZE A3		DRAWING NUMBER 2		E	-
SCALE 1:1	WEIGHT (kg)			D	-
		SHEET 1		C	-
				B	-
				A	-

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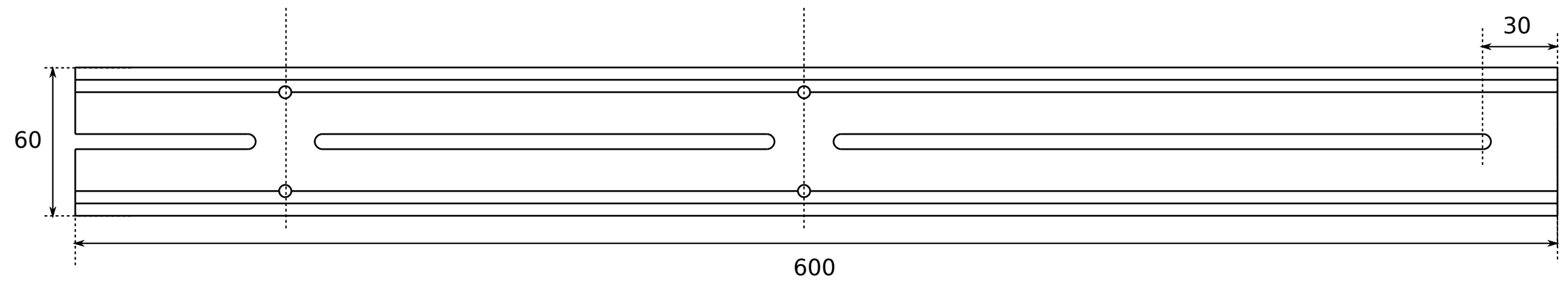
H G B A

H G F E D C B A

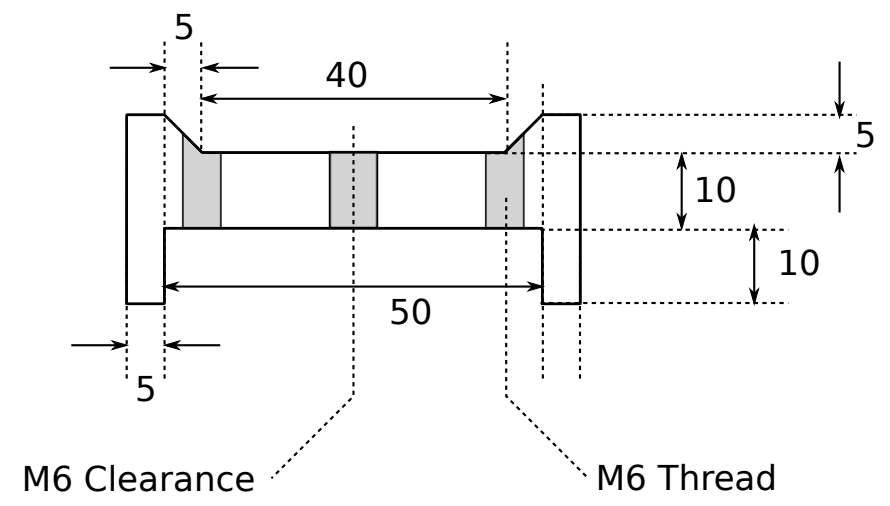
4



3

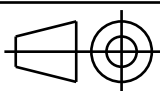



2



1

H G B A

DESIGNED BY: OLIVER FORD		IMSE Carriage		I	-
DATE: 20/06/2012				H	-
CHECKED BY:		Optic Rails		G	-
DATE:				F	-
SIZE A3				E	-
SCALE 1:1	WEIGHT (kg)			D	-
DRAWING NUMBER 3		SHEET 1		C	-
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				A	-

4

3

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1

1

H G F E D C B A

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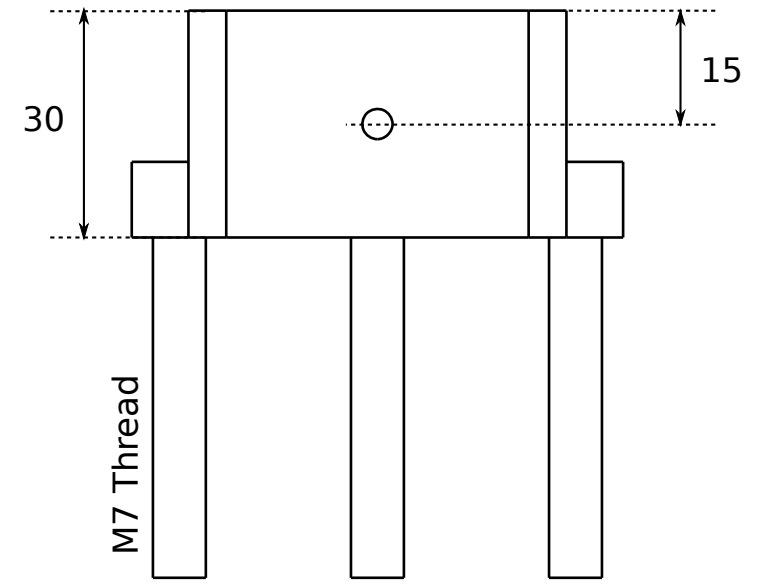
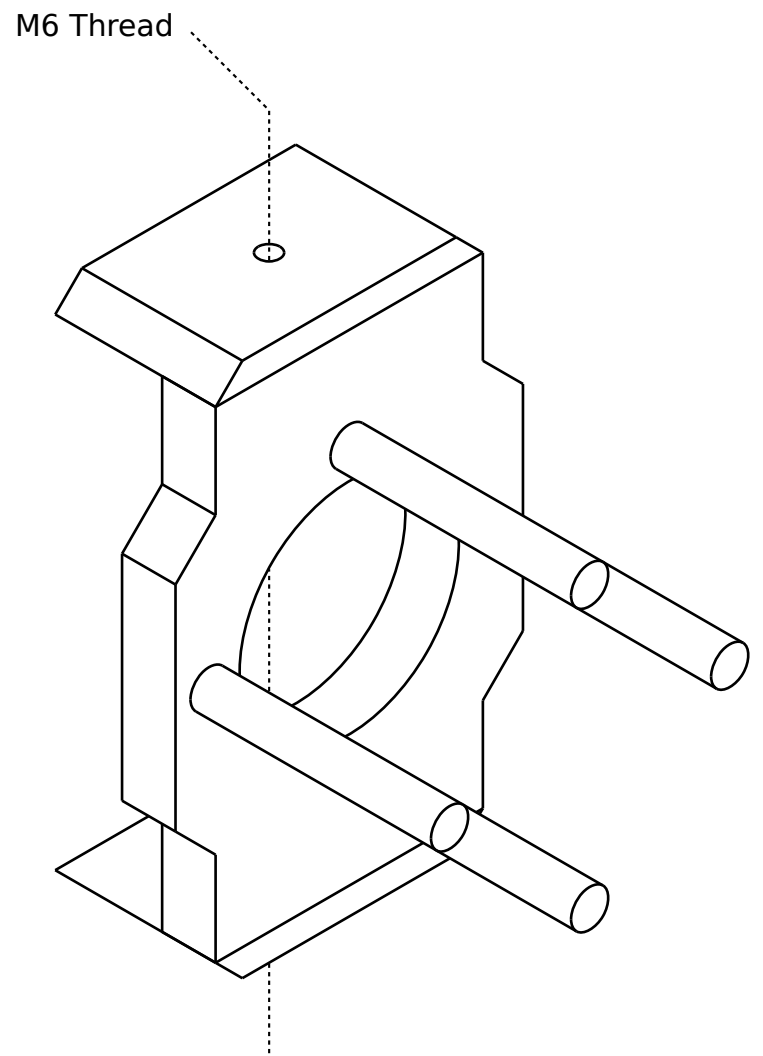
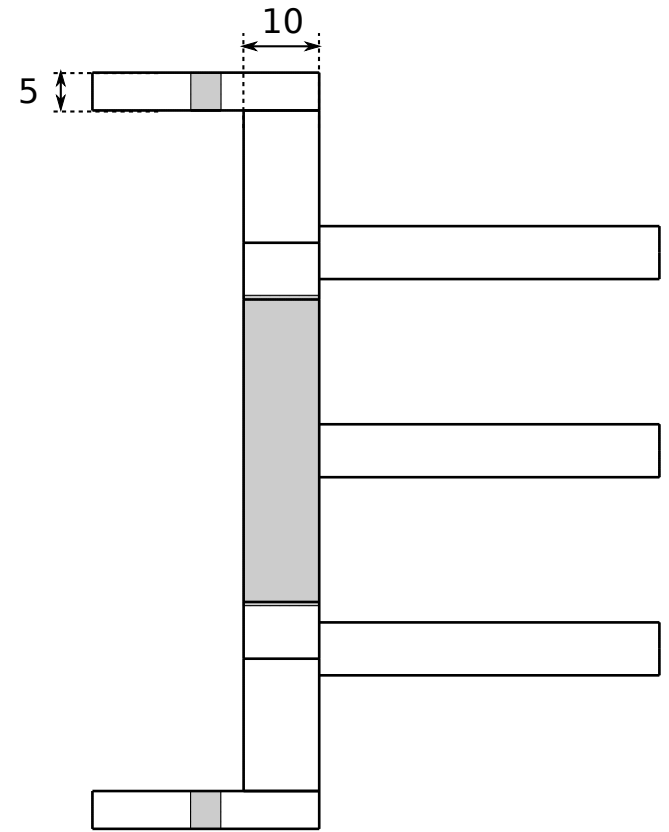
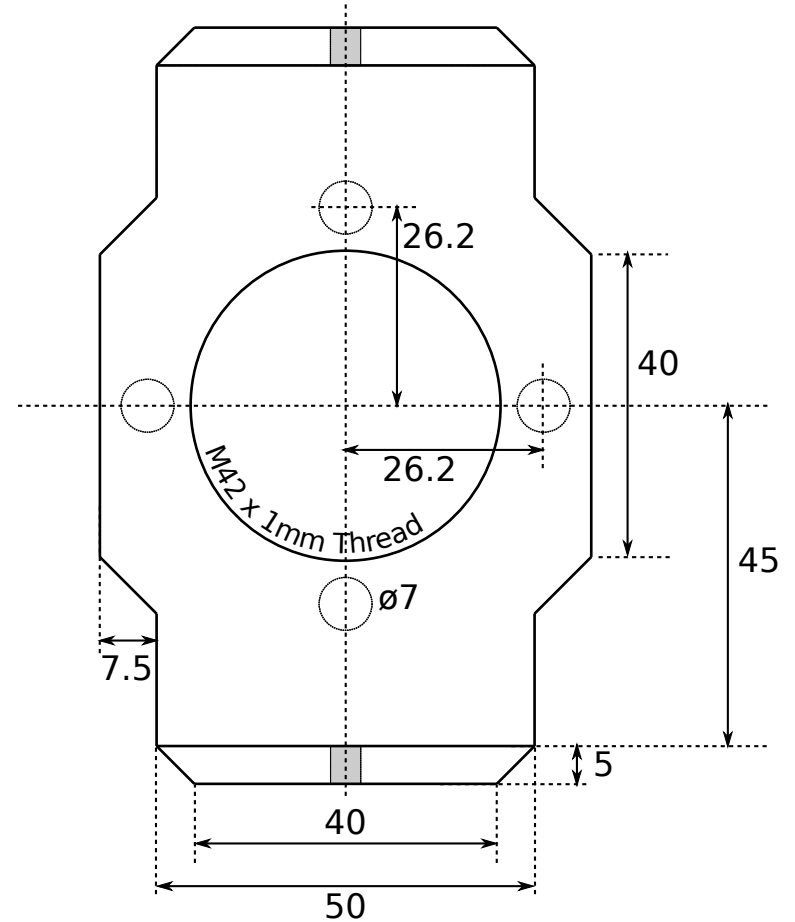
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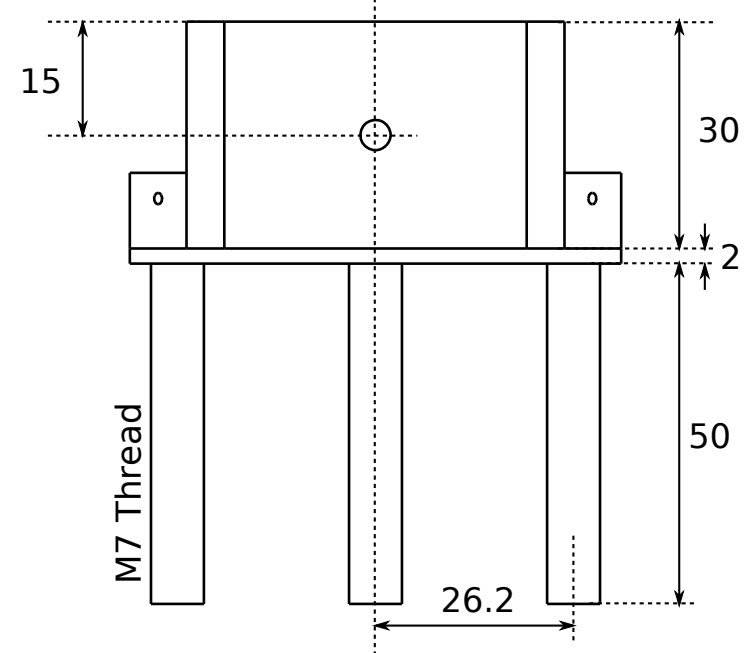
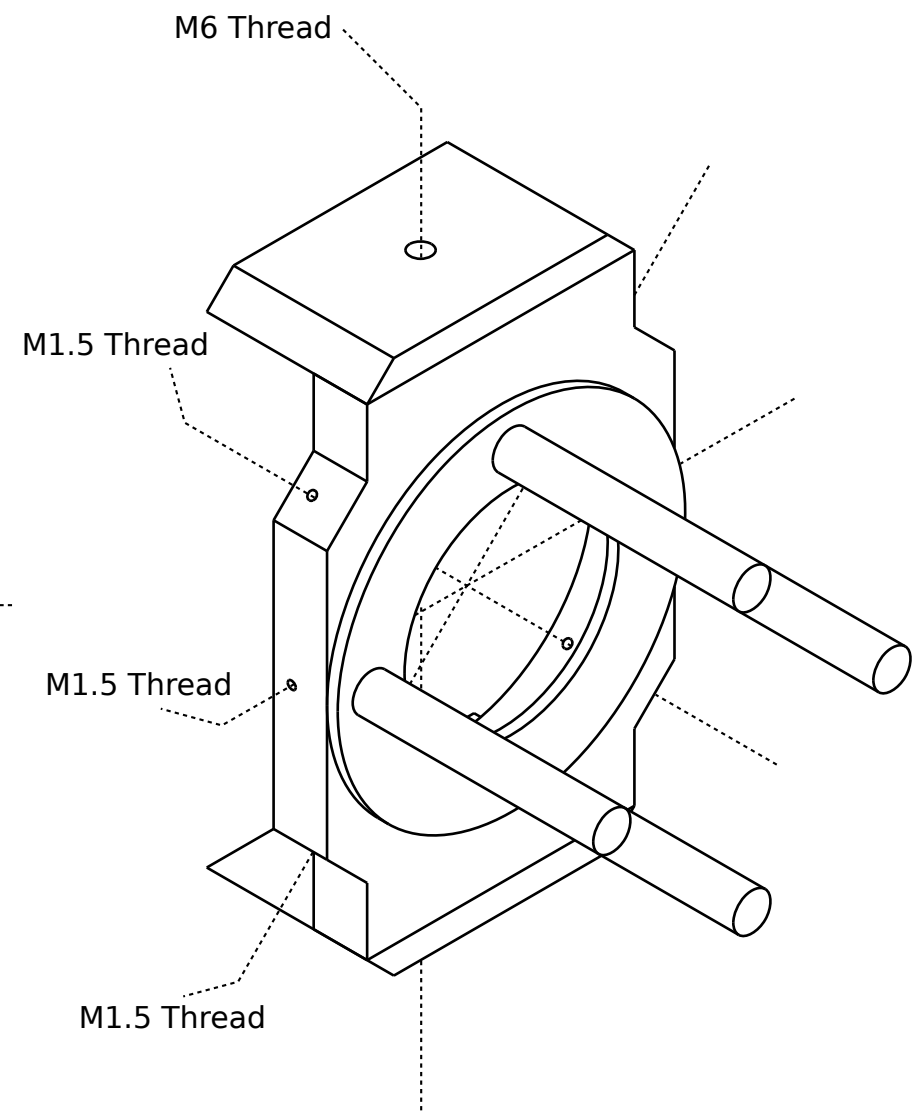
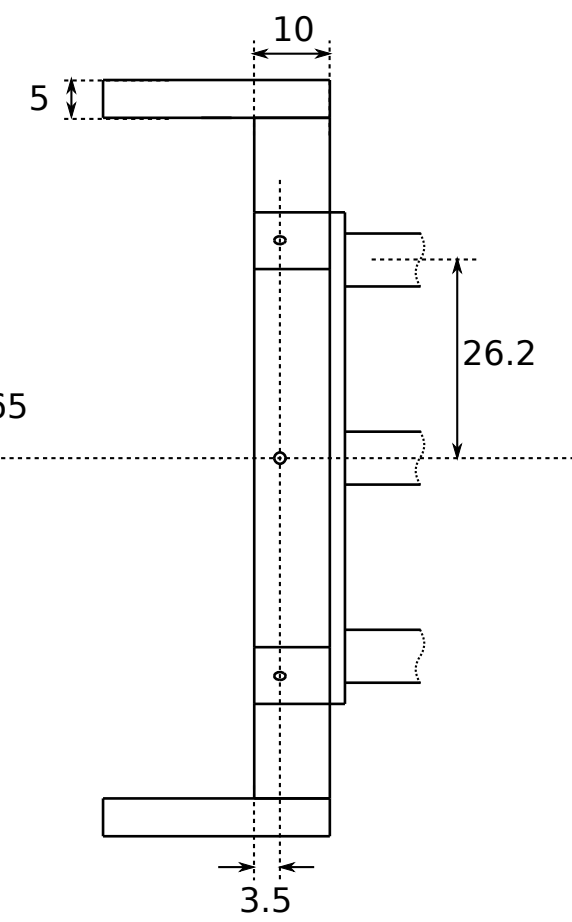
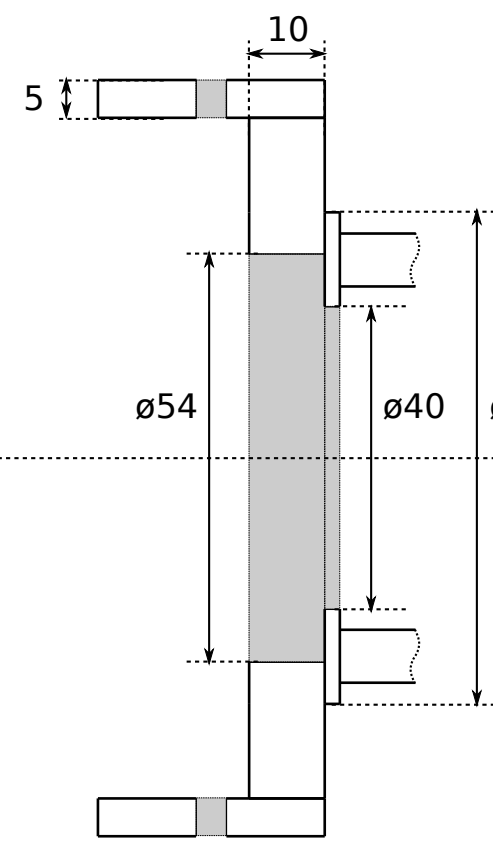
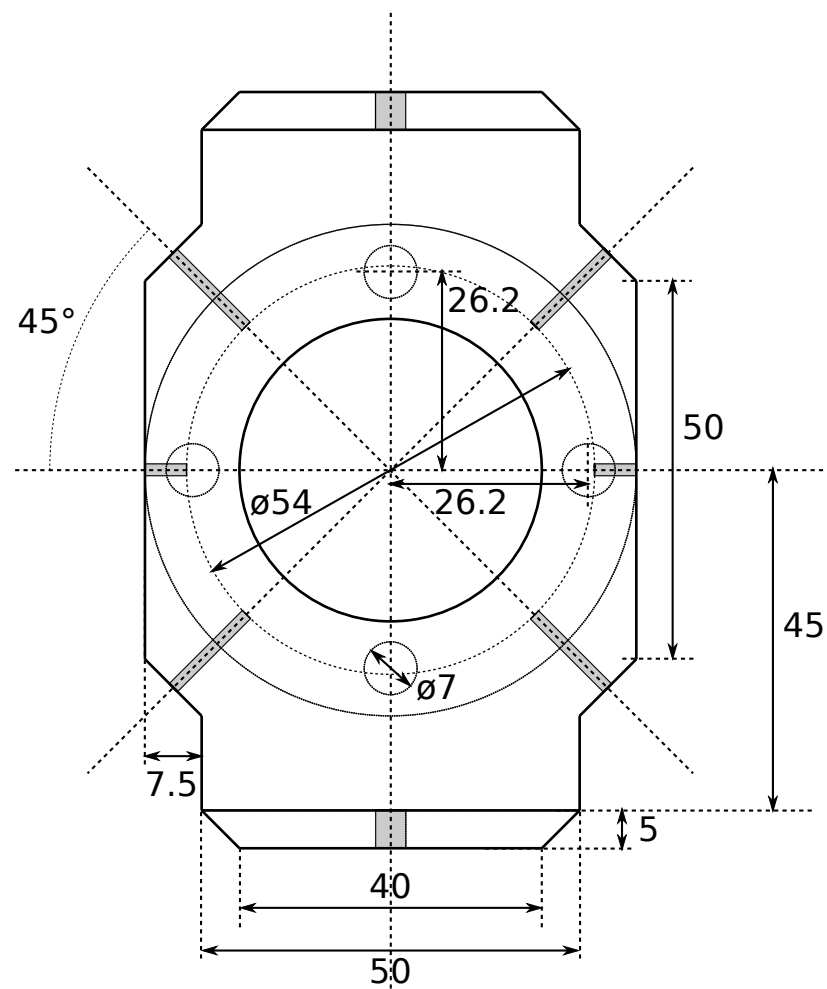
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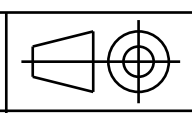
1



DESIGNED BY: OLIVER FORD		IMSE Carriage Lens Mount - M42		I	-
DATE: 22/06/2012				H	-
CHECKED BY:				G	-
DATE:				F	-
SIZE A3		DRAWING NUMBER 4		E	-
SCALE 1:1	WEIGHT (kg)			D	-
		SHEET 1		C	-
				B	-
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H G F E D C B A



DESIGNED BY: OLIVER FORD		IMSE Carriage Lens Mount - Canon EF		I	-
DATE: 22/06/2012				H	-
CHECKED BY:				G	-
DATE:				F	-
SIZE A3		DRAWING NUMBER 5		E	-
SCALE 1:1	WEIGHT (kg)			SHEET 1	
This drawing is our property; it can't be reproduced or communicated without our written agreement.				C	-
				B	-
				A	-

H G F E D C B A

4

3

2

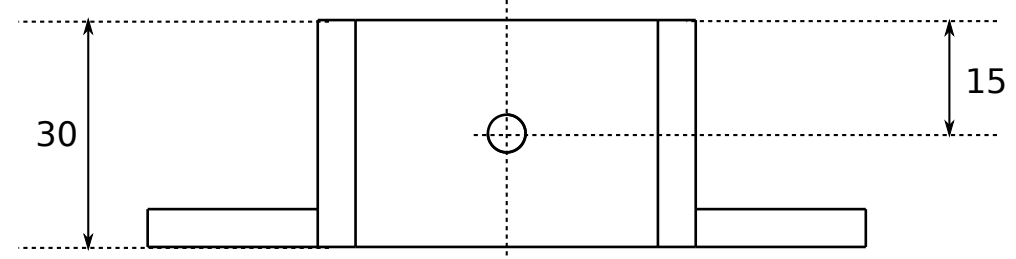
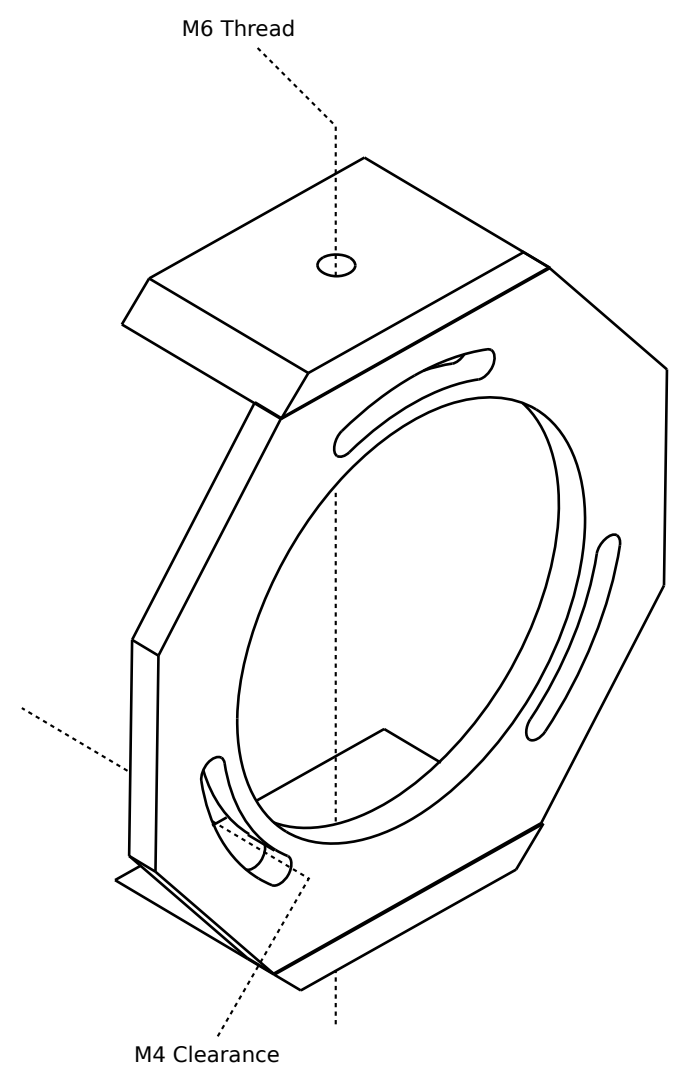
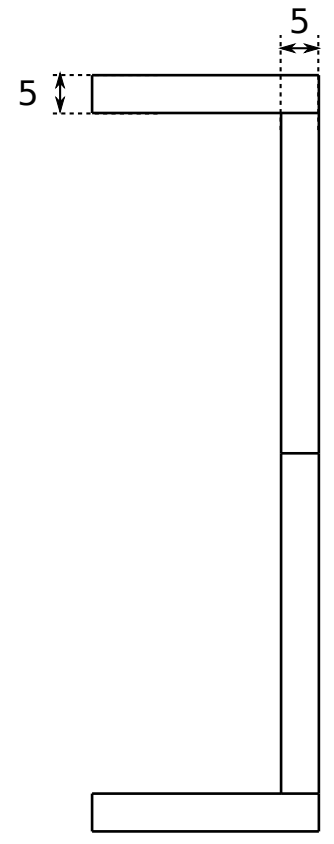
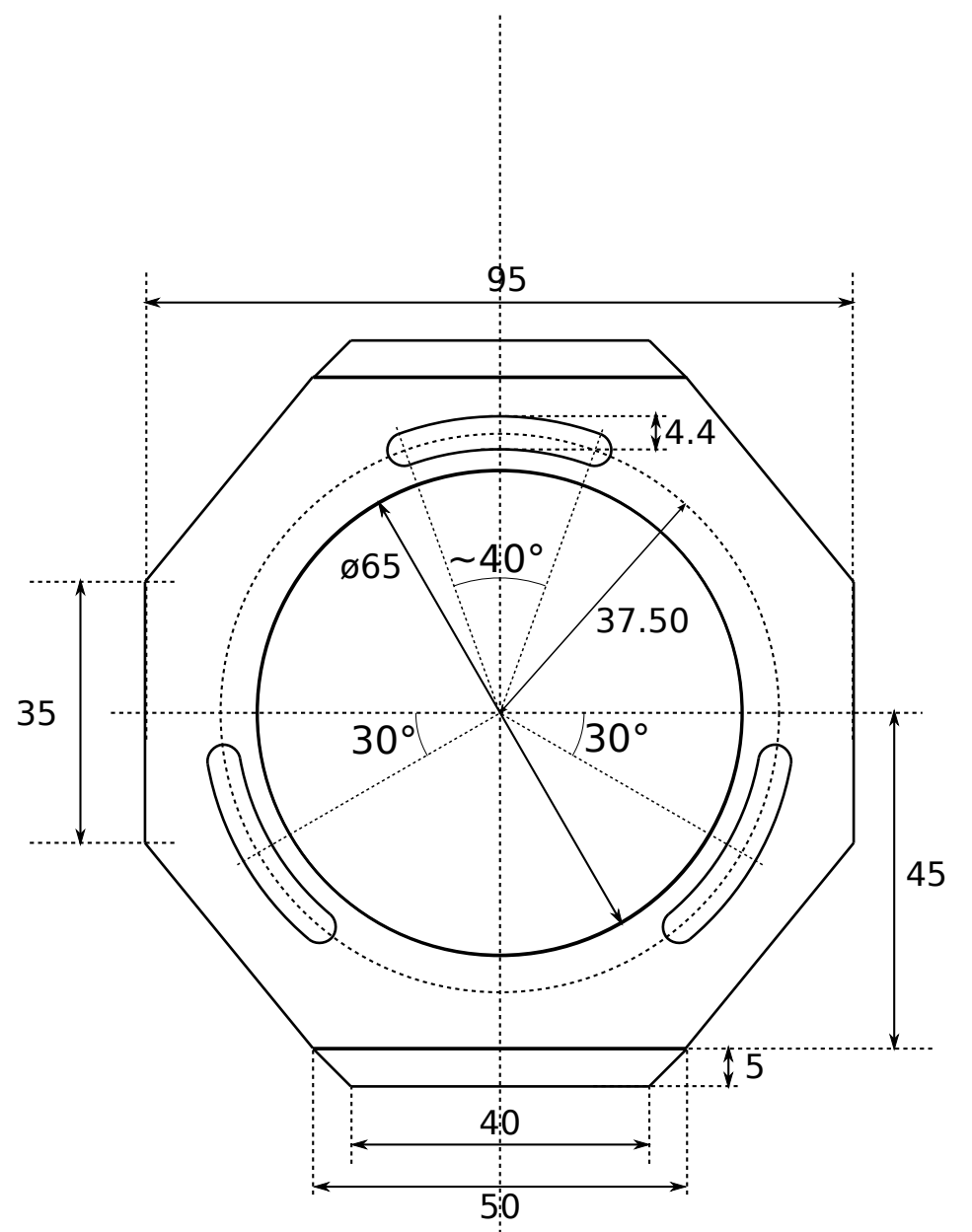
1

4

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2

1



DESIGNED BY: OLIVER FORD		IMSE Carriage Oven Mount		I	-
DATE: 20/06/2012				H	-
CHECKED BY:				G	-
DATE:				F	-
SIZE A3		DRAWING NUMBER 6		E	-
SCALE 1:1	WEIGHT (kg)			D	-
		SHEET 1		C	-
				B	-
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IMSE Design - Mechanical - U1: Calibration Polariser

Upgrade 1 (the week before first experiments in January 2013)

For intrinsic contrast calibration, needed a rotatable polariser.
Need to be switchable in/out by remote control.
Does not need a full rotation - $\sim 135^\circ$ is probably OK.

Jan 2013: Self cut plastic wheel with cable tie as teeth.

April 2014: Laser sintering 3D printer wheel and matching cogs.

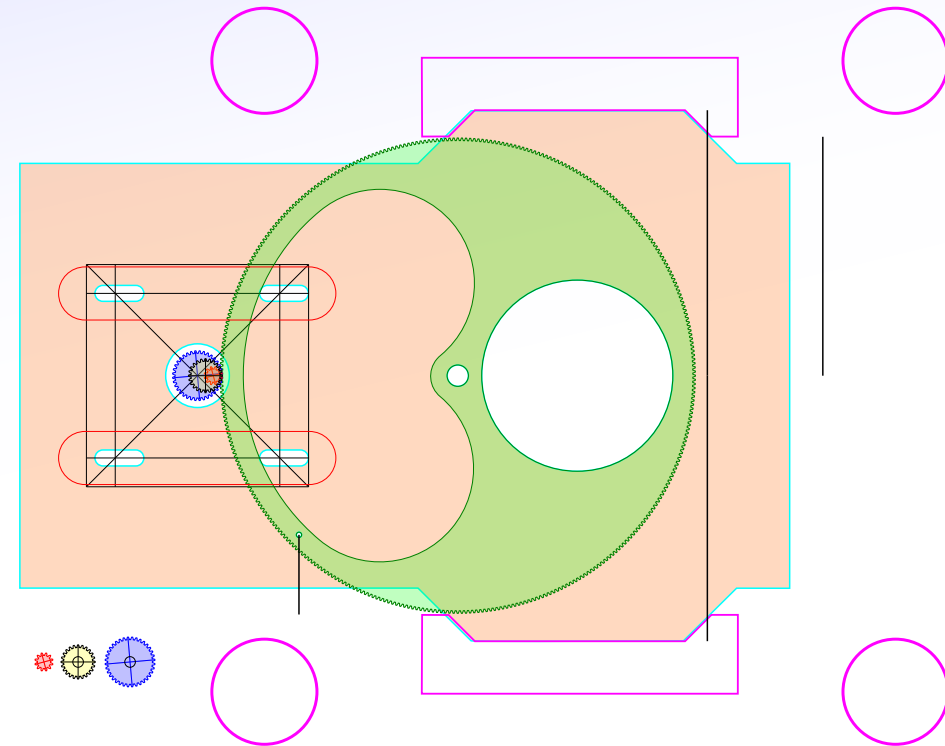
Stepper motor controllers built into IMSE Arduino controller box.
Light barrier and small hole in wheel for zero positioning.

Motor on sprung assembly to maintain tensions.

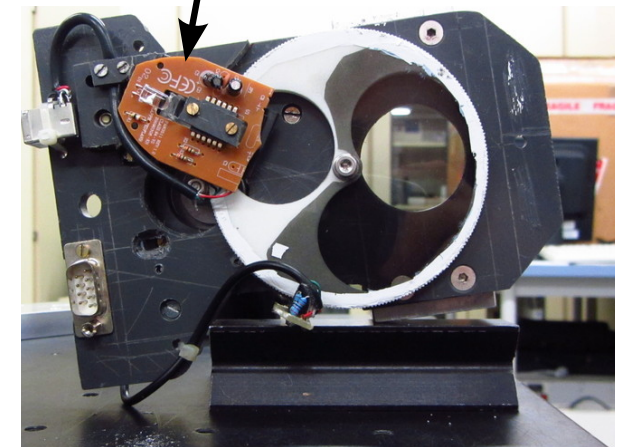
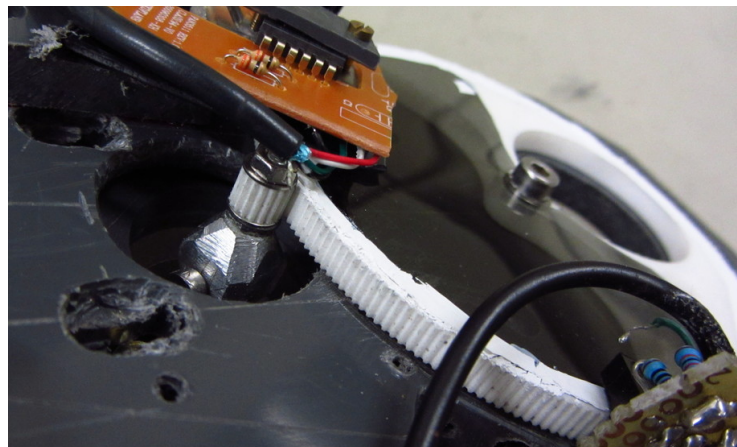
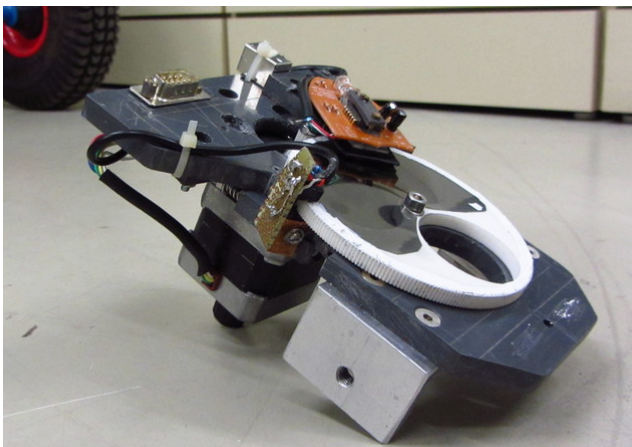
Whole thing seems to be $\pm 0.2^\circ$ linearity and $\pm 0.5^\circ$ reproducibility.

May 2014: Plate was mounted at quite severe angle.

Need better base plate and mounting - get Garching to reproduce.
Needs bearing on wheel to improve linearity.



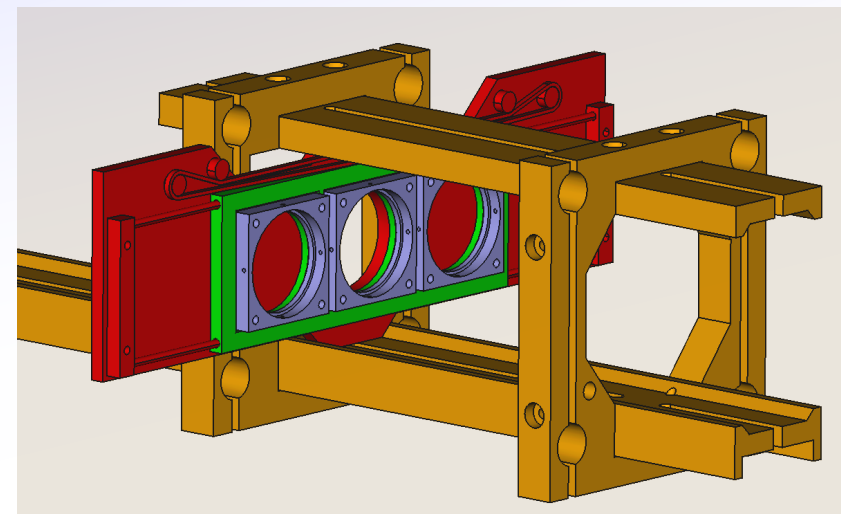
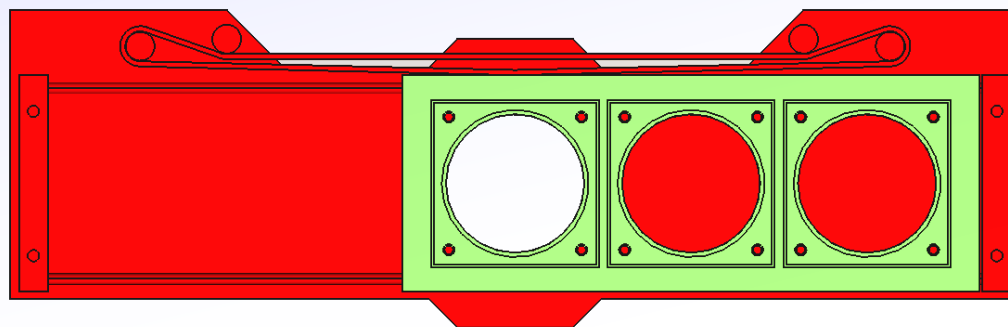
Position sensor using PC Mouse.
Was less accurate than trusting the stepper motor, so removed.



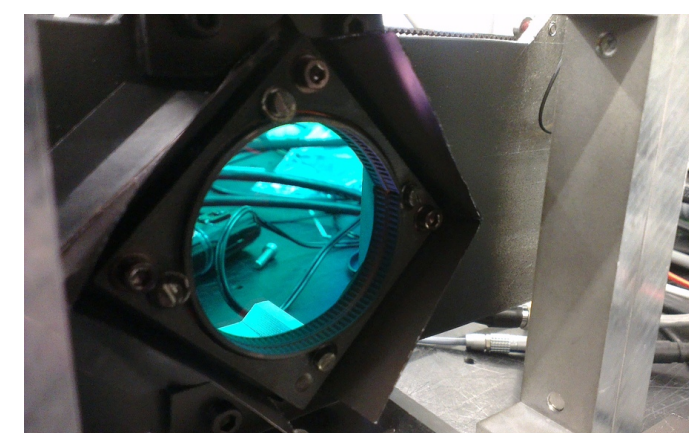
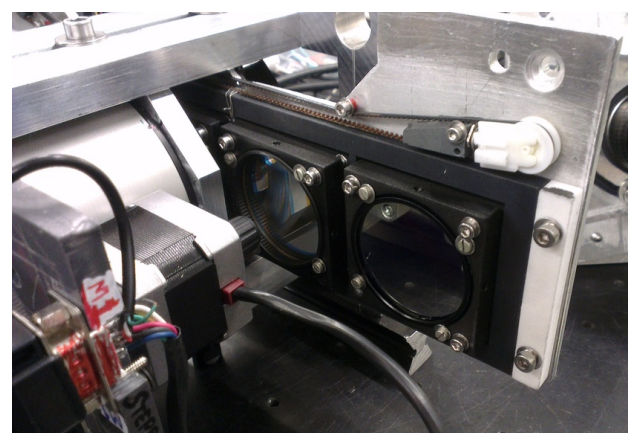
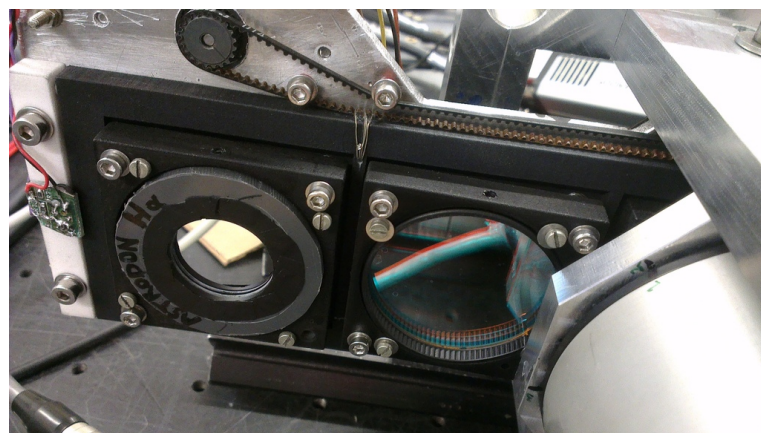
IMSE Design - Mechanical - U2: Filter Slider

Work on cold D/H α Zeeman splitting required different filters. Needs to be switchable remotely. Each filter needs individual 2D tip/tilt adjustment.

An extra common filter for IR blocking - with tip/tilt adjustment is also required.



- Laser sintered parts: 4x holders and 1x tray.
- Self-cut blackplane and mounts.
- 2x 4mm Aluminium bars.
- Stepper motor and belt from an old printer
- Tilt/tip using M3 bolts, nuts and springs from old ball-point pens.



(This is anyway very useful to have for switching filters offline with reproducible tilts)

IMSE Design - Mechanical - U3: Camera Rotation Mount

May2014: New camera (Zyla) needs to be aligned with beam for high speed operation - requires free rotation. Both cameras are too big to fit inside IMSE frame when rotated.

So, cut off the rails and mount camera end-on. Adjustable: Translation in all x,y,z and rotation about y, z .

Complete system now looks like this:

