



Motional Stark Effect Imaging on ASDEX Upgrade: Analysis Notes from Jan 2015

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Equilibrium Stuff





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Polarisation Angle --> Pitch

Measured θ is directly related to pitch (Bz/B ϕ), but lots of things effect both the real and theoretical relationship:

0) Offset

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- Diagnostic geometry
- Mirror position
- Vessel movements
- Plate temperatures
- Beam geometry
- Faraday rotation

1) Linear in (R,Z)

- View geometry
- Beam geometry
- Mirror angle

Should not be required, if the edge field is known (and Er).

(with the new system, we need to make sure we see nearer the edge)

The linear change needs calibrating. In vessel calibration not possible for prototype system so currently trying to calculate it from Equilibrium. This requires knowing Ip and **Axis position**.



2+) Non-linear in (R,Z)

- 2nd+ order instrument effects need eliminating or calibrating where possible!
- Intrinsic contrast (Crystal plate deformations)

Current setup suffers from crystal plate deformations (manufacturing). Ordered better crystals to solve this but they did not arrive in time for this campaign.

Effect depends on light cone so we need illumination as if from the beam (in-vessel work)





Equilibrium

What would we need in the equilbrium to believe we are perfectly predicting the angles? How much do these things really effect it?

- Good magnetics data:
 - TF Correction.
 - Remove Drifts
 - Take care of vessel currents near pickups during fast changes.
 - No mismatch to pre-ignition PF ramps.
 - No non-axisymmetry (Error fields, RMPs?)
- Pressure:
 - Good ne/Te into the core.
 - Relaible from TS but not into centre.
 - Checked Good ECE (Optically thick, good calibration etc)
 - Interferometry in model.
 - Good Ti. CXRS seems good but needs checking.
 - ni ... Zeff???
 - Fast ion pressure (low, or measured)
 - Anisotropy (low fast ions or handled correctly)
- Electric Field
 - Needs $v\phi$ (Ok from CXRS) and $v\theta$ into the core + terms from dP/dp
 - Needs $B\theta$ too (so couples into equi)

All diagnostic input info is in R,Z not ρ so needs to be remapped consistently.

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IMSE / Modelling Notes



Required Model









Electric Field

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Is the electric field important?

Fields are:

- $E\varphi$ = From loop voltage, usually a few V / m not important.
- $E\theta$ = Not sure this should exist. Certainly integral around θ loop is 0, so should be small.
- Er = Radial electric field can be very large.

Er comes equates to (for a given species):

$$E_r = \frac{1}{n_i q_i} \frac{dp_i}{dr} - v_{\theta} B_{\phi} + v_{\phi} B_{\theta}^{\text{Small}}$$

$$\stackrel{\text{Small}}{\underset{\text{Big}}{\text{Big}}}$$

$$\stackrel{\text{Small}}{\underset{\text{Big}}{\text{Big}}}$$

$$\stackrel{\text{Small}}{\underset{\text{Big}}{\text{Big}}}$$

AUG has routine measurements for $v\phi$ but not $v\theta.$

Upper typical values: $B\phi \sim 2.5T$ $B\theta \sim 500mT$ $v\phi \sim 200km/s$ $v\theta \sim 20km/s$ (but can be much larger for ITBs)

Er ~ 50kV/m (up to few 100s kV/m for ITBs)

We need to worry most about $v\phi$.B θ and that alone should be enough to estimate the magnitude, but maybe not to remove it by calculation from the CXRS measured $v\phi$.

Obviously everything is always 0 at the axis.

Also... are $\omega\phi$ and $\omega\theta$ constant(ish) on surfaces??



[H.Meister. Nucl. Fus. 2001]



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Electric Field

What does 100kV/m Er do to the polarisation angle?

Lorenz field is typically $E = v \times B = sqrt(2*60keV / m_p) * 2T \sim 7MV/m$, mostly from B ϕ , so approx vertical. On midplace, Er is approx radial (major R)

